Introduction to Numerical Hydrodynamics and Radiative Transfer

Part II: Hydrodynamics, Lecture 4

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Introduction to Numerical Hydrodynamics

2. The Linear Advection Equation

2.5 Analysis of Numerical Schemes

The Linear Advection Equation – Homework 2

Compute the numerical solution of the linear advection equation

$$\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = 0$$

in the range $0 \le x \le 1$, with the initial conditions

$$\rho_0(x) = 1$$
 for $x < 0$ and $\rho_0(x) = 0$ for $x > 0$

assuming u=1 and $\Delta t/\Delta x = 0.5$, for different numerical schemes: (a) Lax-Friedrichs, (b) Lax-Wendroff and (c) Beam-Warming.

Plot the resulting numerical solutions and the exact analytical solution at time t = 0.5 for the cases $\Delta x = 0.01$ and $\Delta x = 0.0025$, and compare the results to the upwind (donor cell) scheme (see homework 1).

Homework 1 and 2 – Results



Homework 1 and 2 – Results



Homework 1 and 2 – Summary

- Higher spatial and temporal resolution (for given velocity and Courant number) gives a steeper gradient in the numerical solution (i.e., a better correspondence to the exact solution).
- The first order methods (Lax-Friedrichs and upwind/donor cell) give very smeared solutions.
- The second order methods (Lax Wendroff and Beam-Warming) give oscillations.

This qualitatively different behaviour of first and second order methods is typical, and can be understood with the following analysis using modified equations.

General idea:

The discrete equation is an approximation of the original PDE (recall definitions of truncation error and consistency of a scheme)

BUT:

The discrete equation may be an even better approximation of a modified version of the original PDE (corresponding to a higher order of the truncation error).

This modified equation may tell us something about the qualitative behaviour of the numerical scheme ...

Truncation Error

A sufficiently smooth function can be expanded in a Taylor series:

$$\rho(x + \Delta x, t) = \sum_{l=0}^{\infty} \frac{1}{l!} \frac{\partial^{l} \rho}{\partial x^{l}} \Big|_{x,t} \Delta x^{l} = \rho(x, t) + \frac{\partial \rho}{\partial x} \Big|_{x,t} \Delta x + O\left(\Delta x^{2}\right)$$

Solving for $\frac{\partial \rho}{\partial x}$ gives

$$\frac{\partial \rho}{\partial x} = \frac{\rho(x + \Delta x, t) - \rho(x, t)}{\Delta x} + O\left(\Delta x\right)$$

Repeating this for the time derivative and applying it to an entire PDE (FTFS) gives



The order of the truncation error is $O(\Delta t, \Delta x)$ in this case (FTFS). A high order of the truncation error hints at good accuracy for smooth functions.

Example: Lax-Friedrichs method for the linear advection equation

The discrete equation:

$$\frac{1}{\Delta t} \left(\rho_i^{n+1} - \frac{1}{2} \left(\rho_{i-1}^n + \rho_{i+1}^n \right) \right) + \frac{u}{2\Delta x} \left(\rho_{i+1}^n - \rho_{i-1}^n \right) = 0$$

Replacing the discrete solution ρ_i^n with the exact solution $\rho(x,t)$ of the original PDE, we obtain the local truncation error for this numerical scheme:

$$\begin{split} L_{\Delta t,\Delta x}(x,t) &= \frac{1}{\Delta t} \bigg(\rho(x,t+\Delta t) - \frac{1}{2} \big(\rho(x-\Delta x,t) + \rho(x+\Delta x,t) \big) \bigg) \\ &+ \frac{u}{2\Delta x} \big(\rho(x+\Delta x,t) - \rho(x-\Delta x,t) \big) \end{split}$$

Example: Lax-Friedrichs method for the linear advection equation

Taylor expansion about $\rho(x,t)$ gives:

$$\begin{split} L_{\Delta t,\Delta x}(x,t) &= \frac{1}{\Delta t} \Biggl(\left(\rho + \Delta t \frac{\partial \rho}{\partial t} + \frac{1}{2} \Delta t^2 \frac{\partial^2 \rho}{\partial t^2} + \ldots \right) - \left(\rho + \frac{1}{2} \Delta x^2 \frac{\partial^2 \rho}{\partial x^2} + \ldots \right) \\ &+ \frac{u}{2\Delta x} \Biggl(2\Delta x \frac{\partial \rho}{\partial x} + \frac{1}{3} \frac{\partial^3 \rho}{\partial x^3} + \ldots \Biggr) \\ L_{\Delta t,\Delta x}(x,t) &= \frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} + \frac{1}{2} \Biggl(\Delta t \frac{\partial^2 \rho}{\partial t^2} - \frac{\Delta x^2}{\Delta t} \frac{\partial^2 \rho}{\partial x^2} \Biggr) + O(\Delta x^2) \end{split}$$

Example: Lax-Friedrichs method for the linear advection equation

Taylor expansion about $\rho(x,t)$ gives:

$$L_{\Delta t,\Delta x}(x,t) = \frac{1}{\Delta t} \left(\left(\rho + \Delta t \frac{\partial \rho}{\partial t} + \frac{1}{2} \Delta t^2 \frac{\partial^2 \rho}{\partial t^2} + \ldots \right) - \left(\rho + \frac{1}{2} \Delta x^2 \frac{\partial^2 \rho}{\partial x^2} + \ldots \right) + \frac{u}{2\Delta x} \left(2\Delta x \frac{\partial \rho}{\partial x} + \frac{1}{3} \frac{\partial^3 \rho}{\partial x^3} + \ldots \right) \right)$$
$$L_{\Delta t,\Delta x}(x,t) = \underbrace{\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x}}_{0} + \frac{1}{2} \left(\Delta t \frac{\partial^2 \rho}{\partial t^2} - \frac{\Delta x^2}{\Delta t} \frac{\partial^2 \rho}{\partial x^2} \right) + O(\Delta x^2)$$
$$= 0 \quad (\rho \text{ is a solution of the original PDE})$$



Example: Lax-Friedrichs method for the linear advection equation

Taylor expansion about $\rho(x,t)$ gives:

$$\begin{split} L_{\Delta t,\Delta x}(x,t) &= \frac{1}{\Delta t} \Biggl(\left(\rho + \Delta t \frac{\partial \rho}{\partial t} + \frac{1}{2} \Delta t^2 \frac{\partial^2 \rho}{\partial t^2} + \ldots \right) - \left(\rho + \frac{1}{2} \Delta x^2 \frac{\partial^2 \rho}{\partial x^2} + \ldots \right) \Biggr) \\ &+ \frac{u}{2\Delta x} \Biggl(2\Delta x \frac{\partial \rho}{\partial x} + \frac{1}{3} \frac{\partial^3 \rho}{\partial x^3} + \ldots \Biggr) \\ L_{\Delta t,\Delta x}(x,t) &= \frac{1}{2} \Delta t \Biggl(u^2 - \frac{\Delta x^2}{\Delta t^2} \Biggr) \frac{\partial^2 \rho}{\partial x^2} + O(\Delta t^2) \end{split}$$

Example: Lax-Friedrichs method for the linear advection equation

The discrete equation:

$$\frac{1}{\Delta t} \left(\rho_i^{n+1} - \frac{1}{2} \left(\rho_{i-1}^n + \rho_{i+1}^n \right) \right) + \frac{u}{2\Delta x} \left(\rho_{i+1}^n - \rho_{i-1}^n \right) = 0$$

Replacing the discrete solution ρ_i^n with the exact solution $\rho(x,t)$ of the original PDE, and using Taylor expansion, we obtain the local truncation error:

$$L_{\Delta t,\Delta x}(x,t) = \frac{1}{2} \Delta t \left(u^2 - \frac{\Delta x^2}{\Delta t^2} \right) \frac{\partial^2 \rho}{\partial x^2} + O(\Delta t^2)$$

Example: Lax-Friedrichs method for the linear advection equation

The discrete equation

$$\frac{1}{\Delta t} \left(\rho_i^{n+1} - \frac{1}{2} \left(\rho_{i-1}^n + \rho_{i+1}^n \right) \right) + \frac{u}{2\Delta x} \left(\rho_{i+1}^n - \rho_{i-1}^n \right) = 0$$

represents a first order accurate approximation to the original PDE (i.e. the linear advection equation), but a second order accurate approximation to the modified equation

$$\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = \frac{\Delta x^2}{2 \Delta t} \left(1 - \left(u \frac{\Delta t}{\Delta x} \right)^2 \right) \frac{\partial^2 \rho}{\partial x^2}$$

... which is an advection-diffusion equation

 \rightarrow smearing of numerical solutions has a simple explanation!

The advection-diffusion equation

$$\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = D \frac{\partial^2 \rho}{\partial x^2}$$

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with

$$D = \frac{\Delta x^2}{2 \Delta t} \left(1 - \left(u \frac{\Delta t}{\Delta x} \right)^2 \right) \quad \text{(Lax-Friedown or)}$$
or
$$D = \frac{u \Delta x}{2} \left(1 - u \frac{\Delta t}{\Delta x} \right) \quad \text{(upwind (the target products))}$$

(Lax-Friedrichs scheme)

(upwind (donor cell) scheme)

is a second order accurate model for the respective discrete versions of the linear advection equation

 \rightarrow explains typical diffusive behaviour of first order schemes

The advection-diffusion equation

$$\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = D \frac{\partial^2 \rho}{\partial x^2}$$

with

$$D = -\frac{u\Delta x}{2} \left(1 + u\frac{\Delta t}{\Delta x} \right)$$
 (FTFS scheme)
or
$$D = \frac{u\Delta x}{2} \left(1 - u\frac{\Delta t}{\Delta x} \right)$$
 (upwind (donor cell) scheme)

is a second order accurate model for the respective discrete versions of the linear advection equation

 \rightarrow *D*<0 (anti-diffusion) explains problems with FTFS scheme

The dispersive equation

with

$$\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = \mu \frac{\partial^{3} \rho}{\partial x^{3}}$$
(Lax-Wendroff)
or

$$\mu = \frac{u\Delta x^{2}}{6} \left(\left(u \frac{\Delta t}{\Delta x} \right)^{2} - 1 \right)$$
(Lax-Wendroff)

$$\mu = \frac{u\Delta x^{2}}{6} \left(2 - u \frac{3\Delta t}{\Delta x} + \left(u \frac{\Delta t}{\Delta x} \right)^{2} \right)$$
(Beam-Warming)

is a third order accurate model for the respective discrete versions of the linear advection equation

 \rightarrow explains typical oscillations of second order schemes ...

The dispersive equation

with

$$\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = \mu \frac{\partial^{3} \rho}{\partial x^{3}}$$
(Lax-Wendroff)
or

$$\mu = \frac{u\Delta x^{2}}{6} \left(\left(u \frac{\Delta t}{\Delta x} \right)^{2} - 1 \right)$$
(Lax-Wendroff)

$$\mu = \frac{u\Delta x^{2}}{6} \left(2 - u \frac{3\Delta t}{\Delta x} + \left(u \frac{\Delta t}{\Delta x} \right)^{2} \right)$$
(Beam-Warming)

applied to a linear wave with frequency ω and wave number k leads to the dispersion relation, phase velocity and group velocity

$$\omega = u\,k + \mu\,k^3\,, \quad c_p = u + \mu\,k^2 \quad and \quad c_g = u + 3\mu\,k^2$$

The dispersive equation

$$\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = \mu \frac{\partial^3 \rho}{\partial x^3}$$
with

$$\mu < 0 \quad \text{for} \quad \left| u \frac{\Delta t}{\Delta x} \right| < 1 \rightarrow c_g < u \quad \text{(Lax-Wendroff)}$$
or

$$\mu > 0 \quad \text{for} \quad \left| u \frac{\Delta t}{\Delta x} \right| < 1 \rightarrow c_g > u \quad \text{(Beam-Warming)}$$

original PDE (linear advection equation): $\mu = 0 \rightarrow$ no dispersion!

$$\omega = u k \qquad c_p = u \qquad c_g = u$$

Analysis of Schemes – Summary

second order schemes:

modified equation: dispersive equation

$$\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = \mu \frac{\partial^3 \rho}{\partial x^3}$$

 \rightarrow oscillating behaviour of the numerical solution



Analysis of Schemes – Summary

 $\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = \mu \frac{\partial^3 \rho}{\partial x^3}$

second order schemes:

modified equation: dispersive equation

waves: group velocity $c_g = u + 3\mu k^2$

 \rightarrow oscillating behaviour of the numerical solution





Analysis of Schemes – Summary



first order schemes:

modified equation: advection-diffusion equation

$$\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = D \frac{\partial^2 \rho}{\partial x^2}$$

 \rightarrow diffusive behaviour of the numerical solution

Linear Stability Analysis – Original PDE

Lets see what happens to waves in the linear advection equation For the ansatz

$$\rho(x,t) = A(t) e^{-jkx}$$

with $j^2 = -1$ we get

$$\frac{\mathrm{d}A}{\mathrm{d}t} + v\left(-jk\right)A = 0 \ \Rightarrow \ \frac{\mathrm{d}A}{\mathrm{d}t} = jvkA \ \Rightarrow \ A = A_0 e^{jvkt} \ ,$$
$$\rho = A_0 e^{j(\omega t - kx)}$$

with

$$abs(A) = abs(A_0) = const$$
,
 $\omega = vk$.

original PDE (linear advection equation):

- constant amplitude (no growth or decay)
- no dispersion (all waves travel at same speed)

Linear Stability Analysis – General Idea

Linear stability analysis tells about stability - of linear schemes for linear equations.

Linear stability \Rightarrow convergence for consistent schemes Ansatz: for

$$\rho_i^n = e^{-jik\Delta x} \qquad \text{with } j^2 = -1$$

with $k \leq k_0 = \frac{\pi}{\Delta x}$ we search $A \in \mathbb{C}$ with

$$\rho_i^{n+1} = A \, \rho_i^n = A \, e^{-jik\Delta x}$$

Amount abs(A) of $A \Rightarrow damping$ (diffusion) or growth (instability) of waves.

Phase of $A \Rightarrow$ wave speed and dispersion. Ideally $A = e^{j\omega\Delta t}$ with $\omega = vk$.

Linear Stability Analysis – FTCS Scheme

Applying ansatz $\rho_i^n = e^{-jik\Delta x}$

$$A e^{-jik\Delta x} = e^{-jik\Delta x} - \frac{\Delta t}{\Delta x} v \frac{1}{2} \left(e^{-j(i+1)k\Delta x} - e^{-j(i-1)k\Delta x} \right)$$

Multiplying with $e^{jik\Delta x}$ and using the Courant number

$$\alpha := \frac{\Delta t}{\Delta x} v$$

we get

$$A = 1 - \alpha \frac{1}{2} \left(e^{-jk\Delta x} - e^{jk\Delta x} \right) = 1 + j\alpha \sin k\Delta x ,$$
$$\operatorname{abs}(A) = \left(1 + \alpha^2 \sin^2 k\Delta x \right)^{\frac{1}{2}} ,$$

 $\operatorname{abs}(A) > 1$ for $0 < k\Delta x < \pi$, $\alpha > 0$.

All waves except the ones with smallest wavenumber grow exponentially in time: The scheme is unconditionally unstable, independent of the time-step.

Linear Stability Analysis – Donor Cell Scheme

Applying ansatz $\rho_i^n = e^{-jik\Delta x}$ $A = 1 - \alpha \left(1 - e^{jk\Delta x}\right) = 1 - \alpha \left(1 - \cos k\Delta x\right) + j\alpha \sin k\Delta x$, $\operatorname{abs}(A) = \left[1 - 2 \underbrace{\left(\alpha - \alpha^2\right)}_{\geq 0 \text{ for } \alpha \in [0,1]} \underbrace{\left(1 - \cos k\Delta x\right)}_{\geq 0}\right]^{\frac{1}{2}}$,

The donor cell scheme is stable if the CFL condition is fulfilled,

$$rac{\Delta t}{\Delta x} v \in [0,1]$$
 .

 $\operatorname{abs}(A) \leq 1$ for $\alpha \in [0,1]$.

Note: $v \ge 0$ is required (for $v \le 0$ use FTFS).

Note: abs(A) < 1 is possible: numerical viscosity

Note: $phase(A) \neq vk\Delta t$: dispersion

Linear Stability Analysis – Remarks

- Severe restriction: linear PDE and linear scheme
- . Growth of amplitude means instability and stability otherwise
- . Correct solution (constant amplitude) right at the border to instability
- Decline of amplitude indicates numerical viscosity
- Constant amplitude achievable by time-symmetric schemes (but: wiggles, dispersion)

Conclusions:

. No linear scheme is really satisfying.