Introduction to Numerical Hydrodynamics and Radiative Transfer

Part II: Hydrodynamics, Lecture 7

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Introduction to Numerical Hydrodynamics

4. Non-Linear Hydrodynamics

4.1 New Challenges

Equations of Fluid Dynamics: Euler Equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \boldsymbol{u}) = 0$$
$$\frac{\partial}{\partial t} (\rho u_i) + \frac{\partial}{\partial x_j} (\rho u_i u_j + P \delta_{ij}) = 0$$
$$\frac{\partial}{\partial t} \left(\frac{1}{2} \rho u^2 + \rho e \right) + \nabla \cdot \left((\frac{1}{2} \rho u^2 + \rho e + P) \boldsymbol{u} \right) = 0$$

describe the conservation of mass, momentum and energy, based on simplifying physical assumptions:

- no external forces (e.g. gravity, radiation pressure)
- no heating or cooling by radiation or heat conduction
- no viscosity (friction at microscopic level, shear)

Equations of Fluid Dynamics: Euler Equations

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mathematically speaking:

- a coupled system of (up to) 5 non-linear PDEs
- dependent on time and (up to) 3 space dimensions
- hyperbolic conservation laws

Equations of Fluid Dynamics: Euler Equations

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} (\rho u) = 0$$
$$\frac{\partial}{\partial t} (\rho u) + \frac{\partial}{\partial x} (\rho u u + P) = 0$$
$$\frac{\partial}{\partial t} \left(\frac{1}{2} \rho u^2 + \rho e \right) + \frac{\partial}{\partial x} \left((\frac{1}{2} \rho u^2 + \rho e + P) u \right) = 0$$

- a coupled system of 3 non-linear PDEs
- dependent on time and 1 space dimension
- hyperbolic conservation laws

$$\frac{\partial}{\partial t} \mathbf{q} + \frac{\partial}{\partial x} \mathbf{F}(\mathbf{q}) = 0$$
$$\mathbf{q} = \begin{pmatrix} \rho \\ \rho u \\ \frac{1}{2} \rho u^2 + \rho e \end{pmatrix} \mathbf{F} = \begin{pmatrix} \rho u \\ \rho u u + P \\ (\frac{1}{2} \rho u^2 + \rho e + P) u \end{pmatrix}$$

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$$\frac{\partial}{\partial t} \mathbf{q} + \frac{\partial}{\partial x} \mathbf{F}(\mathbf{q}) = 0$$
$$\mathbf{q} = \begin{pmatrix} \rho \\ \rho u \\ \rho e_{tot} \end{pmatrix} \mathbf{F} = \begin{pmatrix} \rho u \\ \rho u + P \\ (\rho e_{tot} + P)u \end{pmatrix}$$

$$\rho e_{tot} = \rho e + \frac{1}{2} \rho u^2$$

$$\rho e_{tot} = \frac{P}{\gamma - 1} + \frac{1}{2} \rho u^2$$

equation of state for polytropic gas:

$$\rho e = \frac{P}{\gamma - 1}$$

Mathematical Properties of PDEs

$$\frac{\partial}{\partial t} \mathbf{q} + \frac{\partial}{\partial x} \mathbf{F}(\mathbf{q}) = 0$$

is a hyperbolic system if the Jacobian matrix of the flux function

$$F'(q) = \frac{\partial F}{\partial q}$$

has the following property: For each value of q the eigenvalues of F'(q) are real, and the matrix is diagonalizable, i.e., there is a complete set of linearly independent eigenvectors.

Mathematical Properties of PDEs $\frac{\partial}{\partial t} q + \frac{\partial}{\partial x} F(q) = 0$ conservative form

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$$\frac{\partial}{\partial t} \mathbf{q} + \mathbf{F}'(\mathbf{q}) \frac{\partial}{\partial x} \mathbf{q} = 0$$

quasilinear form

Mathematical Properties of PDEs

hyperbolic character of system \Rightarrow important consequences for the propagation of information in the flow:

quantities called invariants are transported along characteristics $dx/dt = \lambda$

where λ is an eigenvalue of the Jacobian matrix

$$\boldsymbol{F}'(\boldsymbol{q}) = \frac{\partial \boldsymbol{F}}{\partial \boldsymbol{q}}$$

invariant *r* is constant along the characteristic \Rightarrow

$$\frac{dr}{dt} = \frac{\partial r}{\partial t} + \frac{\partial r}{\partial x} \frac{dx}{dt} = 0 \quad \text{or} \quad \frac{\partial r}{\partial t} + \lambda \frac{\partial r}{\partial x} = 0$$

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example: advection equation (constant velocity u) $\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = 0$ x = u t $r = \rho$

$$\frac{\partial}{\partial t} q + \frac{\partial}{\partial x} F(q) = 0$$

$$q = \begin{pmatrix} \rho \\ \rho u \\ \rho e_{tot} \end{pmatrix} F = \begin{pmatrix} \rho u \\ \rho u u + P \\ (\rho e_{tot} + P)u \end{pmatrix} \qquad \begin{array}{l} \text{equation of state} \\ polytropic gas: \\ \rho e_{tot} = \frac{P}{\gamma - 1} + \frac{1}{2} \rho u^2 \\ 0 & 1 & 0 \\ \frac{1}{2} (\gamma - 3)u^2 & (3 - \gamma)u & (\gamma - 1) \\ \frac{1}{2} (\gamma - 1)u^3 - u(\rho e_{tot} + P)/\rho & (\rho e_{tot} + P)/\rho - (\gamma - 1)u^2 & \gamma u \\ \end{array}$$

Mathematical Properties of PDEs

hyperbolic character of system \Rightarrow important consequences for the propagation of information in the flow:

quantities called invariants are transported along characteristics

$$dx/dt = \lambda$$

where λ is an eigenvalue of the Jacobian matrix



Homework 1 and 2 – Results





The Euler Equations: Numerical Challenges

Positivity of density:

To compute the velocity from momentum and density via $u = (\rho u)/\rho$ requires $\rho > 0$. An overshoot of the density to non-positive values is now disastrous.

Positivity of pressure:

The pressure $P(e,\rho)$ depends on the conserved quantities via

$$e = \frac{\rho e_{tot}}{\rho} - \frac{(\rho u)^2}{2 \rho^2}$$

An overshoot in velocity may lead to negative pressure.

This restriction is so severe that in some cases the conservation of total energy might be given up in favour of a (non-conservative) formulation where the positivity of internal energy is guaranteed.

Introduction to Numerical Hydrodynamics

4. Non-Linear Hydrodynamics

4.2 The Riemann Problem for the 1D Euler Equations

$$\frac{\partial}{\partial t} \mathbf{q} + \frac{\partial}{\partial x} \mathbf{F}(\mathbf{q}) = 0$$

$$\mathbf{q} = \begin{pmatrix} \rho \\ \rho u \\ \frac{1}{2} \rho u^2 + \rho e \end{pmatrix} \qquad \mathbf{F} = \begin{pmatrix} \rho u \\ \rho u u + P \\ (\frac{1}{2} \rho u^2 + \rho e + P) u \end{pmatrix}$$

Riemann problem

- conservation law
- piecewise constant initial condition (discontinuity)

allows for analytical solution \Rightarrow test case for numerical schemes!

The Riemann Problem: Shock Speed



over Δt and Δx results in

 $\int_{x}^{x+\Delta x} \left[q(x,t+\Delta t) - q(x,t)\right] dx + \int_{t}^{t+\Delta t} \left[f(q(x+\Delta x,t)) - f(q(x,t))\right] dt = 0$

For almost constant states and fluxes to the left and right we get

$$\Delta x q_{\rm l} - \Delta x q_{\rm r} + \Delta t f(q_{\rm r}) - \Delta t f(q_{\rm l}) = O(\Delta t^2)$$

For $\Delta x = s \ \Delta t$ and $\Delta t \rightarrow 0$ we get the shock speed

$$s=rac{f(q_{
m r})-f(q_{
m l})}{q_{
m r}-q_{
m l}}$$

Rankine-Hugoniot Conditions

The Rankine-Hugoniot jump conditions for the 1D Euler equations, describing a shock with speed *s*, become

$$s \ [\rho_r - \rho_l] = (\rho u)_r - (\rho u)_l$$

$$s \ [(\rho u)_r - (\rho u)_l] = (\rho u u + P)_r - (\rho u u + P)_l$$

$$s \ [(\rho e + \rho u^2/2)_r - (\rho e + \rho u^2/2)_l] = ((\rho e + \rho u^2/2 + P)u)_r - ((\rho e + \rho u^2/2 + P)u)_l$$

They can only be fulfilled for certain combinations of q_l and q_r . An arbitrary Riemann problem typically causes more than one jump.

The Riemann Problem for the 1D Euler Equations

The state on each side is described by 3 values.

Each wave family can cause a discontinuity:

- sound waves (u±c) can cause shocks or rarefaction waves
- the material flow (u, entropy wave) can have a contact discontinuity

The solution of the Riemann problem (for convex – simple – equation of state) can comprise:

- 0 or 1 contact discontinuity
- 0, 1 or 2 shocks
- 0, 1 or 2 rarefaction waves

not more than 2 (shocks + rarefaction waves)

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4.3 The Shock Tube Problem

Shock Tube Problem: Definition



Shock Tube Problem: Structure of the Solution



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Selected Literature

Selected Literature

General Background

LeVeque, R.J., Numerical Methods for Conservation Laws, Birkhäuser, 1990

Astrophysical Context

LeVeque, R.J., Nonlinear Conservation Laws and Finite Volume Methods, in: Computational Methods for Astrophysical Fluid Flow, Saas-Fee Advanced Course 27, eds. LeVeque R.J., Mihalas D., Dorfi E.A., Müller E., Springer, 1997

Flux Tube Problem

An Introduction to Scientific Computing: Twelve Computational Projects Solved with MATLAB, by I. Danaila, P. Joly, S.M. Kaber and M. Postel, Springer, 2007